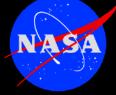
Accessing, Building and Running JEDI



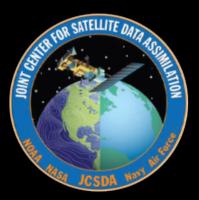






U.S. AIR FORCE

Laptops, Workstations, Clusters, Cloud, HPC



Outline

I) Acquire dependencies

- ✦ JEDI Portability overview
- Software containers
- + HPC environment modules
- + Cloud

II) Build JEDI

- + JEDI bundles
- CMake, ecbuild

Note: in today's practicals you will not need to build JEDI - you will only run it. But, knowing how to access, build, and run JEDI may help you *after* today



How can I Run JEDI?

Application container

 A software container that includes JEDI and all it's dependencies, ready to run

Development container

Includes JEDI dependencies - you download and build JEDI yourself

Pre-Made Environment Modules

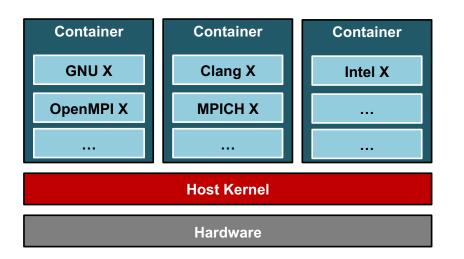
- JEDI dependencies available on Hera, Orion, Discover, S4, Cheyenne, Gaffney, and the Amazon cloud (through AMIs)
- You download and build JEDI yourself

Build your own Environment Modules

- Jedi-stack build system: <u>https://github.com/JCSDA/jedi-stack</u>
- You build JEDI and all of its dependencies

What is a container?

Software container (working definition) A packaged user environment that can be "unpacked" and used across different systems, from laptops to cloud to HPC



Container benefits

- Portability
- Reproducibility
 - Version control (git)
- Bring your own environment
- Efficiency / workflow
 - Develop on laptops, run on HPC/cloud
 - Get new users up and running quickly

JEDI Software Dependencies

- Essential
 - + Compilers, MPI
 - CMake
 - + SZIP, ZLIB
 - + LAPACK / MKL, Eigen 3
 - NetCDF4, HDF5
 - + udunits
 - Boost (headers only)
 - + ecbuild, eckit, fckit
 - + bufr
- ► Useful
 - + PNETCDF
 - Parallel IO
 - + nccmp, NCO
 - Python tools (netcdf4, matplotlib, cartopy...)
 - json-schema-validator

What do the containers and modules contain?

Common versions among users and developers minimize stack-related debugging

Environment Modules

Example: Discover (NCCS)

(base) mmiesch@discover34:~> module purge (base) mmiesch@discover34:~> module load jedi/intel-impi (base) mmiesch@discover34:~> module list Currently Loaded Modules: 1) git/2.24.0 9) udunits/2.2.26 17) eigen/3.3.7 2) git-lfs/2.10.0 10) mpi/impi/19.1.0.166 18) bufrlib/11.3.2 3) jedi-python/3.8.3 11) jedi-impi/19.1.0.166 19) cmake/3.17.0 4) comp/gcc/9.2.0 12) hdf5/1.12.0 20) ecbuild/jcsda-3.3.2.jcsda3 5) comp/intel/19.1.0.166 13) pnetcdf/1.12.1 21) eckit/jcsda-1.11.6.jcsda2 6) jedi-intel/19.1.0.166 14) netcdf/4.7.4 22) nco/4.7.9 7) szip/2.1.1 15) nccmp/1.8.7.0 23) pio/2.5.1-debug 8) zlib/1.2.11 16) boost-headers/1.68.0 24) jedi/intel-impi/19.1.0.166-v0.4

jedi-stack leverages native compilers and mpi libraries Other stack components are built from these

Container Technologies

Docker

- Main Advantages: industry standard, widely supported, runs on native Mac/Windows OS
- Main Disadvantange: Security (root privileges)

Singularity

- Main Advantages: Reproducibility, HPC support
- Main Disadvantage: Not available on all HPC systems
- Preferred platform for scientific applications



JCSDA provides a public ubuntu 18.04 AMI that comes with Singularity, Charliecloud, and Docker pre-installed





Current containers

Development

- + gnu-openmpi-dev (D, S, C)
- + clang-mpich-dev (D, S, C)
- + intel-oneapi-dev (DIY)

Application

- Tutorial (S)
- + intel 19 and 2021 One API (S)

singularity pull <u>library://jcsda/public/jedi-gnu-openmpi-dev</u> singularity shell -e jedi-gnu-openmpi_latest.sif

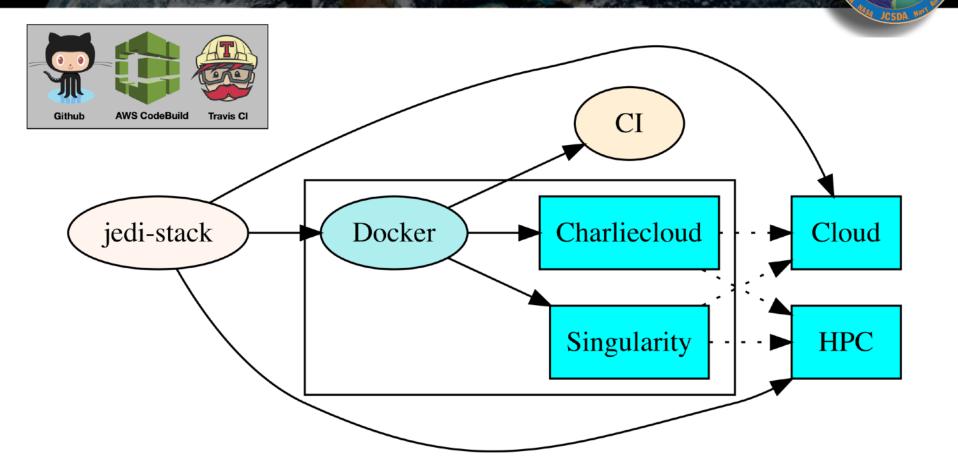
http://data.jcsda.org/pages/containers.html



Docker Hub Sylabs cloud AWS S3 (public)



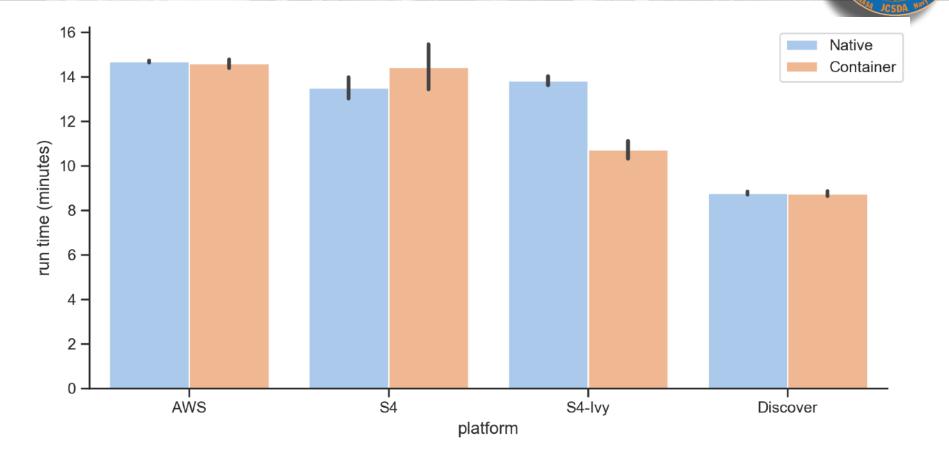
Unified Build System



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Tagged jedi-stack releases can be used to build tagged containers, AMIs, and HPC environment modules, ensuring common software environments across platforms

Supercontainers!



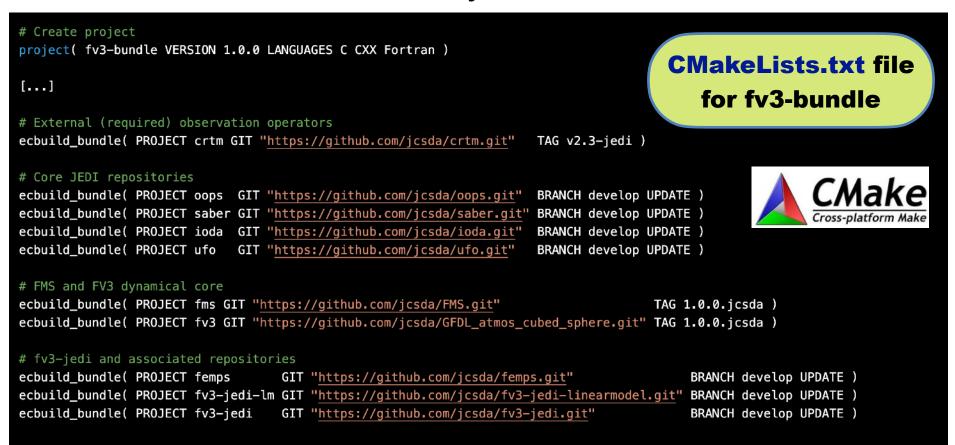
With a little care, containers can be run across nodes on HPC systems with no overhead JEDI 3DVar Application 864 MPI tasks, 12M observations FV3-gfs c192

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II: JEDI Build System

The JEDI is code organized into <u>bundles</u> that identify all the GitHub repositories necessary to build and run the applications

CMake build system: <u>ecbuild</u> = CMake macro package developed and maintained by ECMWF



Building a Bundle

git clone <u>https://github.com/JCSDA/fv3-bundle.git</u>
mkdir build
cd build
ecbuild ../fv3-bundle
make update
make -j4
ctest

2

3

4

5

6

- 1. Download the bundle repository from GitHub
- 2. Create a build directory
- 3. Run ecbuild (CMake) to generate a build system
- 4. Pull the latest source code from GitHub
- 5. Compile
- 6. Run the test suite for the bundle

Running a JEDI Application

Each application just takes a single configuration file as input, in yaml format

Define JEDI bin directory where the executables are found export jedibin=\$HOME/jedi/build/bin # Run the BUMP parameter scripts to produce the B matrix mpirun -np 6 \$jedibin/fv3jedi_parameters.x config/bumpparameters_nicas_gfs.yaml # Run the variational application mpirun -np 18 \$jedibin/fv3jedi_var.x config/4denvar.yaml # Compute the increment for plotting mpirun -np 6 \$jedibin/fv3jedi_diffstates.x config/4denvar-increment.yaml

A JEDI Configuration file

cost function:

cost type: 4D-Ens-Var analysis variables: [ua,va,T,ps,sphum,ice_wat,liq_wat,o3mr] window begin: '2018-04-14T21:00:00Z' window length: PT6H subwindow: PT3H background: states: - filetype: gfs datapath: /opt/jedi/build/fv3-jedi/test/Data/inputs/gfs_c12/bkg/ filename_core: 20180414.210000.fv_core.res.nc filename trcr: 20180414.210000.fv tracer.res.nc filename_sfcd: 20180414.210000.sfc_data.nc filename_sfcw: 20180414.210000.fv_srf_wnd.res.nc filename_cplr: 20180414.210000.coupler.res state variables: [ua,va,T,ps,sphum,ice_wat,lig_wat,o3mr,phis, slmsk,sheleg,tsea,vtype,stype,vfrac,stc,smc,snwdph,

u_srf,v_srf,f10m]

[...]

observations:

```
- obs space:
name: AMSUA-NOAA19
obsdatain:
obsfile: /opt/jedi/build/fv3-jedi/test/Data/obs/testinput_tier_1/amsua_n19_obs_2018041500_m.nc4
simulated variables: [brightness_temperature]
channels: 10
obs operator:
name: CRTM
Absorbers: [H20,03]
obs options:
Sensor_ID: amsua_n19
```

A taste of what a <u>JEDI configuration file</u> looks like (you'll see more in the other lectures and activities)

SATELLITE DATA

Contributing to JEDI

Source code

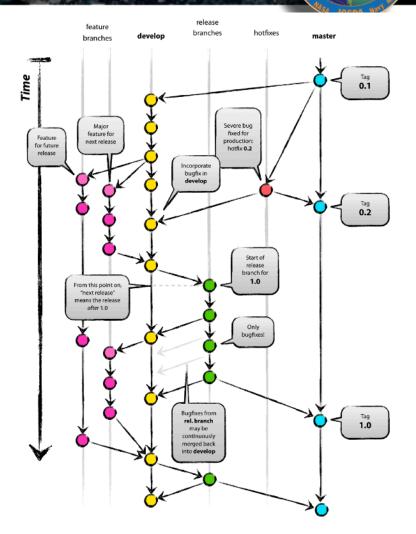
https://github.com/JCSDA

Code Contributions handled via Pull Requests

- Work from forks
- Use git-flow branch naming conventions
- Document and test your code
- Expect Code reviews, CI testing

User/Developer forums

https://forums.jcsda.org



https://nvie.com/posts/a-successfulgit-branching-model/ **JEDI User/Developer Manual**

IE JEDI Documentation — JEDI Do 🗙 🕂 G 0 A https://jointcenterforsatellitedataassimilation-jedi-docs.readthedocs-hoste ... ⊠ ☆ III\ 🗉 🔍 **# JEDI Documentation** C Edit on GitHub **Docs** » JEDI Documentation Search docs http://jedi-docs.jcsda.org **JEDI Documentation** Overview Working Principles Welcome to the Joint Effort for Data assimilation Integration (JEDI)! Learning JEDI JEDI is a unified and versatile data assimilation (DA) system for Earth System Using JEDI Prediction. The Goals and code organization — X + Inside JEDI from laptops to: \rightarrow C' $\hat{\mathbf{n}}$ 0 🖴 https://jointcenterforsatellitedataassimilation-jedi-docs.readthedocs-hosted.com 🖻 (120%) 🛛 💀 😒 🏠 IIN 🗉 🛎 Frequently Asked Questions (FAQ) learning DA fund algorithms and c References Three categories of background error covariance models are currently implemented Search docs in BUMP: oceanic research accommodate n Overview • The ensemble covariance model is built as a transformed and localized sample systems. Working Principles covariance matrix: Learning JEDI $\mathbf{B}_{e} = \mathbf{T} \left(\mathbf{T}^{-1} \widetilde{\mathbf{B}} \mathbf{T}^{-T} \circ \mathbf{L} \right) \mathbf{T}^{\mathrm{T}}$ Using JEDI JEDI is develope Assimilation, a n B Inside JEDI where: ⊟ JEDI Components • $\widetilde{\mathbf{B}} \in \mathbb{R}^{n \times n}$ is the sample covariance matrix estimated from an ensemble, Corporation for • $\mathbf{T} \in \mathbb{R}^{n \times n}$ is an invertible transformation matrix. OOPS improving and a • $\mathbf{L} \in \mathbb{R}^{n \times n}$ is the localization matrix. B SABER satellite data in v o odenotes the Schur product (element-by-element). BUMP prediction system The static covariance model is build with successive parametrized operators: IODA UFO $\mathbf{B}_{s} = \mathbf{U}_{b} \mathbf{\Sigma} \mathbf{C} \mathbf{\Sigma} \mathbf{U}_{b}^{\mathrm{T}}$ JEDI is a commu FV3-JEDI where: document serve Configuring JEDI • $\mathbf{U}_h \in \mathbb{R}^{n \times n}$ is a multivariate balance operator, • $\Sigma \in \mathbb{R}^{n \times n}$ is a diagonal matrix containing standard deviations. Read the Docs v: latest -Read the Docs If you have ques $\mathbf{C} \in \mathbb{R}^{n \times n}$ is a block diagonal (univariate) correlation matrix.

SATELLITE DAY

Questions Welcome