

# Model Interfacing

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26<sup>th</sup> February 2020



U.S. AIR FORCE

# Outline



- Introduction
- Model space classes
- GetValues
- Building an application
- LinkedLists (not presented)

# Introduction



OOPS provides the algorithms that combine generic building blocks into applications such as variational assimilation, forecast, EnKF, FSOI etc.

OOPS (by design) knows nothing about the actual implementation of the building blocks and carries no information about the underlying data. The classes that need to be implemented for a specific model are called interface classes.

Often models are written in Fortran so a mixed language approach is required and a binding between the languages is implemented.

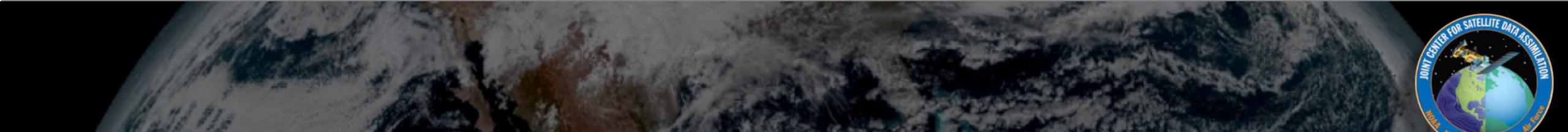
Once the interface to a specific model is ready it can be used to create applications by passing traits and information about factories.



# Models being interfaced to JEDI



MODEL	TYPE	INTERFACE	CENTER
FV3GFS	Atmosphere	fv3-jedi	NOAA-EMC
GEOS	Atmosphere	fv3-jedi	NASA-GMAO
FV3GFS GSDChem	Atmospheric chemistry	fv3-jedi	NOAA-ESRL
GEOS-AERO	Atmospheric aerosols	fv3-jedi	NASA-GMAO
MPAS	Atmosphere	mpas	NCAR
WRF	Atmosphere	wrf-jedi	NCAR
LFRic	Atmosphere	lfric	Met Office (UK)
MOM6	Ocean	soca	NOAA-EMC
SIS2	Sea ice	soca	NOAA-EMC
CICE6	Sea ice	soca-cice6	NOAA-EMC
NEPTUNE	Atmosphere	neptune	NRL
QG	Toy model	oops	ECMWF
Lorenz 95	Toy model	oops	ECMWF
ShallowWater	Toy model	shallow-water	NOAA-ESRL



# Model space classes

# Geometry Class: OOPS vs. FV3-JEDI



## OOPS (GENERIC)

```
template <typename MODEL>
class Geometry {
    typedef typename MODEL::Geometry Geometry_;

public:

    Geometry(const eckit::Configuration &, const eckit::mpi::Comm &);
    Geometry(const Geometry &);
    explicit Geometry(boost::shared_ptr<const Geometry_>);
    ~Geometry();

    /// Interfacing
    const Geometry_ & geometry() const {return *geom_;}

private:
    boost::shared_ptr<const Geometry_> geom_;
};
```

## MODEL (SPECIFIC)

```
class Geometry : public util::Printable,
                 private util::ObjectCounter<Geometry> {
public:
    static const std::string classname() {return "fv3jedi::Geometry";}

    explicit Geometry(const eckit::Configuration &, const eckit::mpi::Comm &);
    Geometry(const Geometry &);
    ~Geometry();

    GeometryIterator begin() const;
    GeometryIterator end() const;

    F90geom & toFortran() {return keyGeom_;}
    const F90geom & toFortran() const {return keyGeom_;}
    const eckit::mpi::Comm & getComm() const {return comm_;}

private:
    Geometry & operator=(const Geometry &);
    void print(std::ostream &) const;
    F90geom keyGeom_;
    const eckit::mpi::Comm & comm_;
};
```

# Geometry method



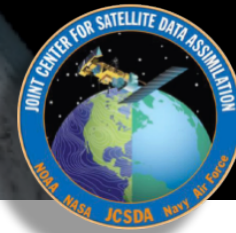
C++ Model, State, Increment etc.

```
Geometry::Geometry(const eckit::Configuration & conf, const eckit::mpi::Comm & comm) : comm_(comm) {  
    const eckit::Configuration * configc = &conf;  
  
    dx_ = conf.getInt("dx")  
    dy_ = conf.getInt("dy")  
  
}
```

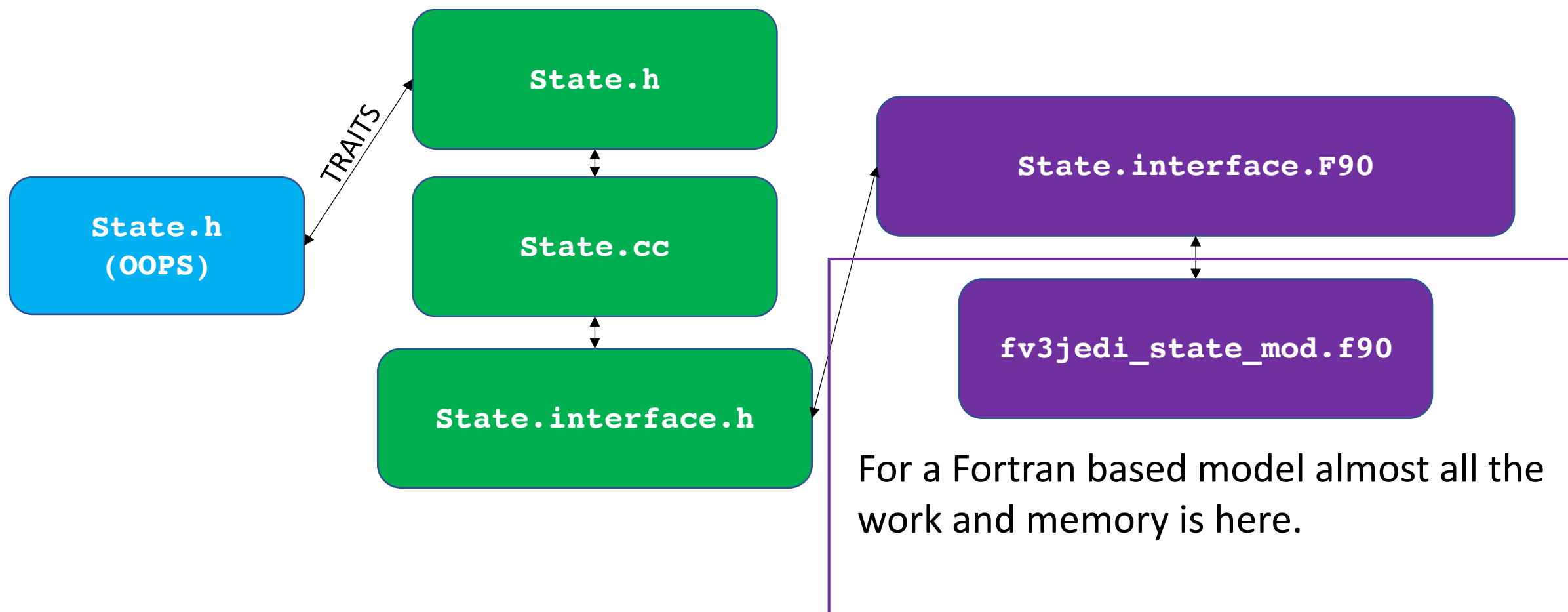
Fortran Model, State, Increment etc.

```
Geometry::Geometry(const eckit::Configuration & conf, const eckit::mpi::Comm & comm) : comm_(comm) {  
    const eckit::Configuration * configc = &conf;  
  
    interface(keyGeom_, &configc, &comm_);  
  
}
```

# C++ to Fortran Binding Files



All the model (and UFO) classes follow basically the same file structure for the mixed C++/Fortran languages:





# Binding



```
Geometry::Geometry(const eckit::Configuration & conf, const eckit::mpi::Comm & comm) : comm_(comm) {  
    const eckit::Configuration * config = &conf;  
  
    interface(keyGeom_, &config, &comm_);  
}
```

Integer locating  
this geometry  
object

Pointer to  
configuration  
object

Pointer to  
communicator  
object

# Config binding



```
subroutine c2f_binding(c_key_self, c_comm, c_conf, c_vars)

integer(c_int), intent(in) :: c_key_self
type(c_ptr),    intent(in) :: c_conf
type(c_ptr),    intent(in) :: c_comm
type(c_ptr),    intent(in) :: c_vars

type(interface)      :: f_self
type(fckit_configuration) :: f_conf
type(fckit_mpi_comm)   :: f_comm
type(oops_variables)   :: f_vars

call fv3jedi_geom_registry%get(c_key_self, f_self)

f_comm = fckit_mpi_comm(c_comm)
f_conf = fckit_configuration(c_conf)
f_vars = oops_variables(c_vars)

call f_self%implementation(f_comm, f_conf, f_vars)

end subroutine c2f_binding
```

```
subroutine implementation(comm, conf, vars)

class(interface), intent(inout) :: self
type(fckit_configuration), intent(in) :: conf
type(fckit_mpi_comm),      intent(in) :: comm
type(oops_variables),      intent(in) :: vars

...
call conf%get_or_die("yaml_input", self%data)

end subroutine implementation
```

The implementation is pure Fortran and is where the work is done

The interface is constructed once, potentially just by copying from some other model.

# Example Fortran interfaces for Geometry



```
module fv3jedi_geom_mod

implicit none
private
public :: fv3jedi_geom
public :: create, clone, delete, info
! -----
type :: fv3jedi_geom
  integer :: something
end type fv3jedi_geom
! -----
contains

subroutine create(self, c_conf)
implicit none
type(fv3jedi_geom), intent(inout) :: self
type(c_ptr),          intent(in)   :: c_conf
end subroutine create
```

```
subroutine clone(self, other)
implicit none
type(fv3jedi_geom), intent(in  ) :: self
type(fv3jedi_geom), intent(inout) :: other
end subroutine clone

subroutine delete(self)
implicit none
type(fv3jedi_geom), intent(inout) :: self
end subroutine delete

end module fv3jedi_geom_mod
```



# Geometry Class: Fortran Type



!> Fortran derived type to hold geometry data for the FV3JEDI model

```
type :: fv3jedi_geom
  integer :: isd, ied, jsd, jed           !data domain
  integer :: isc, iec, jsc, jec           !compute domain
  integer :: npz, npy, npz                !x/y/z-dir grid edge points per tile
  integer :: layout(2)                    !Processor layout for computation
  integer :: io_layout(2)                  !Processor layout for read/write
  integer :: halo                          !Number of halo points, normally 3
  character(len=255) :: nml_file           !FV3 nml file associated with this geom
  integer :: size_cubic_grid               !Size of cubed sphere grid (cell center)
  type(domain2D) :: domain                 !MPP domain
  integer :: ntile                         !Tile ID
  integer :: ntiles = 6                    !Number of tiles, always 6
  integer :: stackmax                      !Stackmax
  real(kind=kind_real), allocatable :: grid_lon(:, :) !Longitude at cell center
  real(kind=kind_real), allocatable :: grid_lat(:, :) !Latitude at cell center
  real(kind=kind_real), allocatable :: egrid_lon(:, :) !Longitude at cell center
  real(kind=kind_real), allocatable :: egrid_lat(:, :) !Latitude at cell center
  real(kind=kind_real), allocatable :: area(:, :)      !Grid area
  real(kind=kind_real), allocatable :: ak(:), bk(:)    !Model level coefficients
  real(kind=kind_real) :: ptop              !Pressure at top of domain
end type fv3jedi_geom
```



# Geometry Class: Fortran Methods



```
subroutine create(self, c_conf)

implicit none

!Arguments
type(fv3jedi_geom), intent(inout) :: self
type(c_ptr), intent(in) :: c_conf

!Locals
type(fv_atmos_type), allocatable :: FV_Atm(:)

!Initialize using the model setup routine
call fv_init(FV_Atm, 300.0_kind_real, grids_on_this_pe, p_split)
deallocate(pelist_all)

self%isc = FV_Atm(1)%bd%isc
self%iec = FV_Atm(1)%bd%iec
self%jsc = FV_Atm(1)%bd%jsc
self%jec = FV_Atm(1)%bd%jec
self%ntile = FV_Atm(1)%tile

self%npx = FV_Atm(1)%npx
self%npy = FV_Atm(1)%npy
self%npz = FV_Atm(1)%npz
self%layout(1) = FV_Atm(1)%layout(1)
self%layout(2) = FV_Atm(1)%layout(2)

!Lat,lon and area from
allocate ( self%area(self%isd:self%ied, self%jsd:self%jed) )
allocate ( self%grid_lon(self%isd:self%ied, self%jsd:self%jed) )
allocate ( self%grid_lat(self%isd:self%ied, self%jsd:self%jed) )

self%area = FV_Atm(1)%gridstruct%area_64
self%grid_lon = real(FV_Atm(1)%gridstruct%agrid_64(:, :, 1), kind_real)
self%grid_lat = real(FV_Atm(1)%gridstruct%agrid_64(:, :, 2), kind_real)

end subroutine create
```

Call to dynamical core

```
subroutine clone(self, other)

implicit none

type(fv3jedi_geom), intent(in) :: self
type(fv3jedi_geom), intent(inout) :: other

allocate(other%grid_lon(self%isd:self%ied, self%jsd:self%jed))
allocate(other%grid_lat(self%isd:self%ied, self%jsd:self%jed))
[]
other%npx = self%npx
other%npy = self%npy
other%npz = self%npz
other%layout = self%layout
other%grid_lon = self%grid_lon
other%grid_lat = self%grid_lat

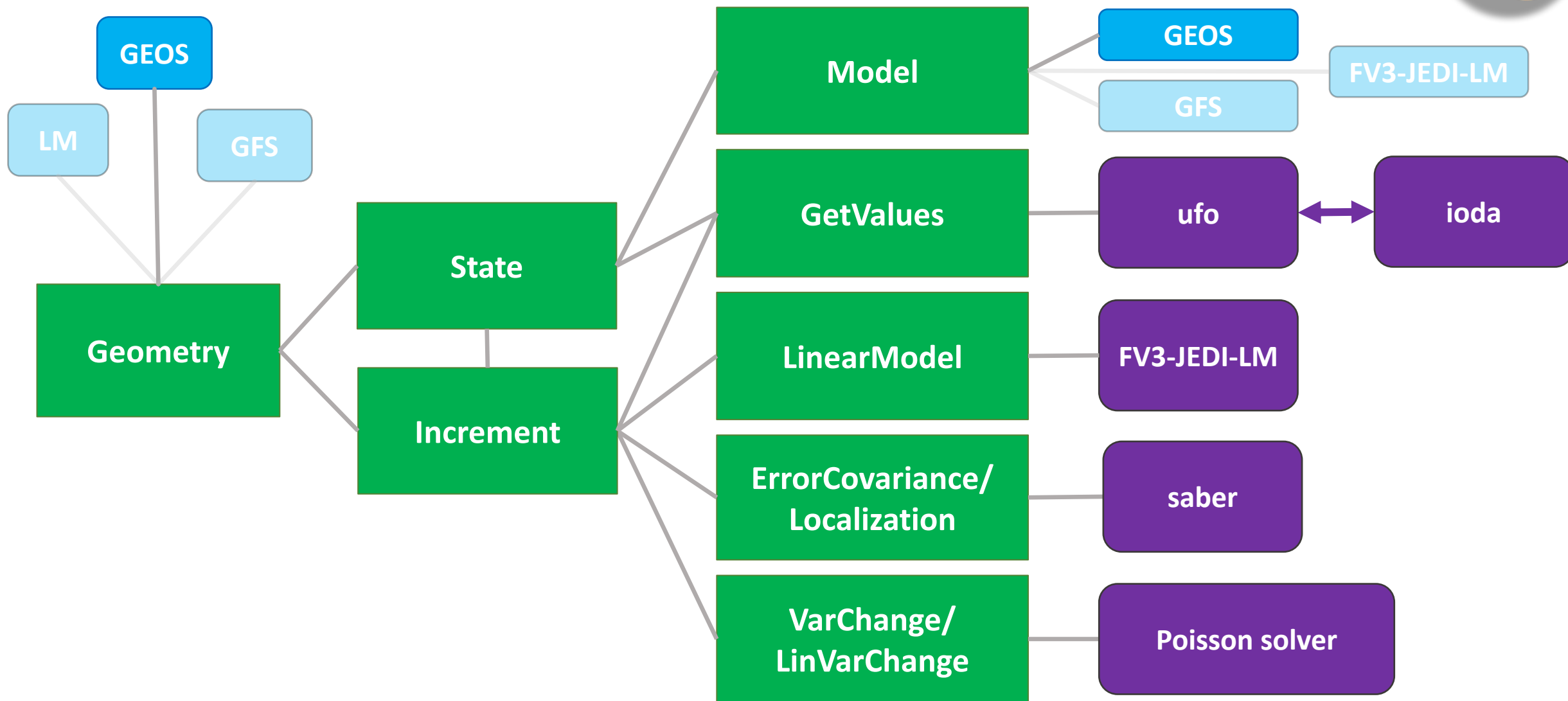
subroutine delete(self)
implicit none
type(fv3jedi_geom), intent(inout) :: self

! Deallocate
deallocate(self%grid_lon)
deallocate(self%grid_lat)
deallocate(self%egrid_lon)
deallocate(self%egrid_lat)
deallocate(self%area)
deallocate(self%ak)
deallocate(self%bk)

call mpp_deallocate_domain(self%domain)

end subroutine delete
```

# Dependency structure



# State and Increment: Methods



State

Fields

Increment

axpy  
add\_increment  
analytic\_ic

create  
delete  
zeros  
copy  
read  
write  
gpnorm  
rms  
change\_res

random  
self\_add (+=)  
self\_schur  
self\_sub (-=)  
self\_mul (\*=)  
axpy\_inc  
axpy\_state  
dot\_prod  
diff\_states  
ug\_coord  
increment\_to\_ug  
ug\_to\_increment  
dirac

# Example Fortran Field Class



The concept of fields is introduced in order to limit duplicate code across sate and increment.

Some model interfaces implement fields at the C++ level, e.g. qg, l95, soca. Some do so at the Fortran level, e.g. fv3-jedi, mpas, lfrc.

```
!Field type
type :: fv3jedi_field
  logical :: lalloc = .false.
  character(len=32) :: short_name = "null" !Short name (to match file name)
  character(len=10) :: fv3jedi_name = "null" !Common name
  character(len=64) :: long_name = "null" !More descriptive name
  character(len=32) :: units = "null" !Units for the field
  logical :: tracer = .false.
  integer :: staggerloc !Middle, corners, east, south, etc
  integer :: isc, iec, jsc, jec, npz
  real(kind=kind_real), allocatable :: array(:,:,:)
contains
  procedure :: allocate_field
  procedure :: array_pointer
  procedure :: equals
  generic :: assignment(=) => equals
  procedure :: deallocate_field
endtype fv3jedi_field
```



# State/Increment variables



```
type :: fv3jedi_state

    !Local copies of grid for convenience
    integer :: isc, iec, jsc, jec
    integer :: npx, npy, npz
    integer :: ntiles, ntile
    logical :: hydrostatic = .true.
    integer :: calendar_type, date_init(6)
    integer :: nf
    logical :: have_agrid
    logical :: have_dgrid

    type(fv3jedi_field), allocatable :: fields(:)

end type fv3jedi_state
```

# State/Increment constructor



```
subroutine create(self, geom, vars)

implicit none
type(fv3jedi_state), intent(inout) :: self
type(fv3jedi_geom), intent(in) :: geom
type(oops_vars), intent(in) :: vars

integer :: var, vcount

self%nf = vars%nv

allocate(self%fields(self%nf))

vcount = 0
do var = 1, vars%nv
  select case (trim(vars%fldnames(var)))
    case("ud", "u", "U")
      vcount=vcount+1;
      call self%fields(vcount)%allocate_field(geom%isc,geom%iec,geom%jsc,geom%jec,geom%npz, &
        short_name = vars%fldnames(var), long_name = 'eastward_wind_on_native_D-Grid', &
        fv3jedi_name = 'ud', units = 'm s-1', staggerloc = north, arraypointer = self%ud )
    case("...")
      ...
    case default
      call abort1_ftn("Create: unknown variable "//trim(vars%fldnames(var)))
  end select
enddo

end subroutine create
```

Incoming vars are decided by the user at run time.

Variables are pre-programmed but not hardwired

# State/Increment method



```
subroutine self_schur(self,rhs)

implicit none
type(fv3jedi_increment), intent(inout) :: self
type(fv3jedi_increment), intent(in)    :: rhs

integer :: var

call checksame(self%fields,rhs%fields,"fv3jedi_increment_mod.self_schur")

do var = 1,self%nf
  self%fields(var)%array = self%fields(var)%array * rhs%fields(var)%array
enddo

end subroutine self_schur
```

Optionally check  
same list of fields in  
self and rhs

Loop through all  
allocated fields. Not  
dependent on  
variables chosen.

# The Forecast Model



- Jedi is designed to work with the Model *in-core*. That is to say that JEDI will drive the model through the assimilation window exchanging states as it goes.
- This is often one of the hardest parts of interfacing JEDI to a particular forecast model.
- Forecast models have not necessarily been developed in a way that exposes a stepping method, the model states themselves and with an ability to ‘rewind’, as is needed for outer loops.
- Political issues can also present themselves.



# Model class



```
// -----  
static oops::ModelMaker<FV3JEDITraits, ModelGEOSFV3JEDI> makermodel_("GEOS");  
// -----  
ModelGEOSFV3JEDI::ModelGEOSFV3JEDI(const GeometryFV3JEDI & resol,  
                                     const eckit::Configuration & mconf)  
    : keyConfig_(0), tstep_(0), geom_(resol), vars_(mconf)  
{  
    oops::Log::trace() << "ModelGEOSFV3JEDI::ModelGEOSFV3JEDI" << std::endl;  
    tstep_ = util::Duration(mconf.getString("tstep"));  
    const eckit::Configuration * configc = &mconf;  
  
    // JEDI to GEOS directory  
    getcwd(jedidir_, 10000);  
  
    std::string sGEOSSCRDIR = mconf.getString("GEOSSCRDIR");  
    strcpy(geosscrdir_, sGEOSSCRDIR.c_str());  
    chdir(geosscrdir_);  
  
    // Create the model  
    fv3jedi_geos_create_f90(&configc, geom_.toFortran(), keyConfig_);  
  
    // GEOS to JEDI directory  
    chdir(jedidir_);  
  
    oops::Log::trace() << "ModelGEOSFV3JEDI created" << std::endl;  
}
```

Factory name

# Model class



```
type :: geos_model
  type(MAPL_Cap) :: cap
  integer :: GEOSsubsteps
end type geos_model
```

GEOS

```
type :: nems_model
  type(ESMF_GridComp) :: esmComp !NUOPC driver
  type(ESMF_State)     :: importState, exportState
  type(ESMF_Clock)     :: clock
  integer :: dt
  character(len=20) :: startTime
end type nems_model
```

NEMSfv3gfs

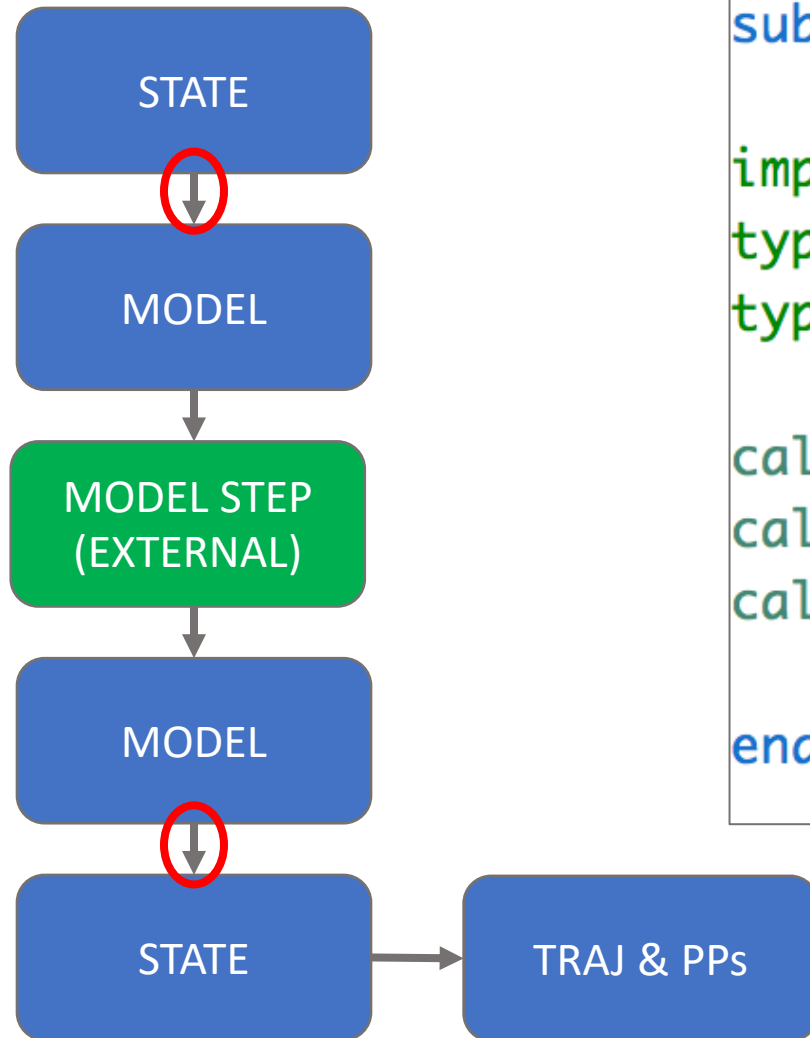
```
type :: fv3_model
  type(fv3jedi_lm_type) :: fv3jedi_lm
end type fv3_model
```

Dynamical core only

```
type :: pseudo_model
  character(len=255) :: pseudo_type !geos of gfs
  character(len=255) :: pseudo_path
  character(len=255) :: pseudo_file
end type pseudo_model
```

Pseudo model

# Data flow



```
subroutine model_step(self, state)

implicit none
type(fv3jedi_model), intent(inout) :: self
type(fv3jedi_state), intent(inout) :: state

call state_to_lm(state, self%fv3jedi_lm)
call self%fv3jedi_lm%step_nl()
call lm_to_state(self%fv3jedi_lm, state)

end subroutine model_step
```

Can be pointer, move or copy.  
Usually a copy to account for  
differences in precision

# LinearModel class

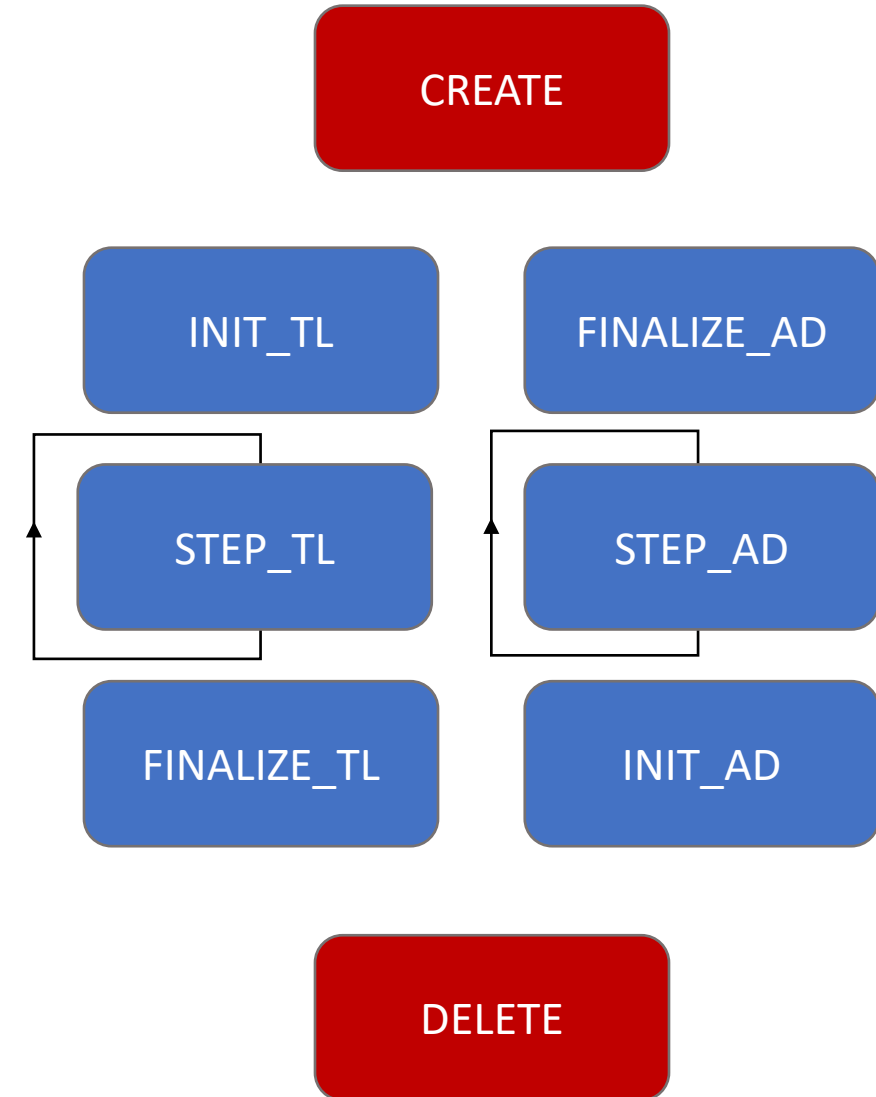


```
type:: fv3jedi_tlm
  type(fv3jedi_lm_type) :: fv3jedi_lm
end type fv3jedi_tlm
```

```
public :: fv3jedi_tlm
public :: tlm_create
public :: tlm_delete
public :: tlm_initialize_tl
public :: tlm_initialize_ad
public :: tlm_step_tl
public :: tlm_step_ad
public :: tlm_finalize_tl
public :: tlm_finalize_ad
```

Per outer  
loop

Per inner  
loop





# Variable changes



Incremental hybrid-4DVar involves a number of linear and nonlinear variable transforms:

$$\frac{\partial J}{\partial \delta \mathbf{x}_0} = \mathbf{B}^{-1} (\delta \mathbf{x}_0 - \delta \mathbf{x}_b) - \sum_{k=0}^K \mathbf{K}_m^\top \mathbf{M}_k^\top \mathbf{K}_h^\top \mathbf{H}^\top \mathbf{R}_k^{-1} (\mathbf{d}_k - \mathbf{H} \mathbf{K}_h \delta \mathbf{x}_k)$$

$$\delta \mathbf{x}_k = \mathbf{M}_{t_{k-1} \rightarrow t_k} \mathbf{M}_{t_{k-1} \rightarrow t_{k-2}} \cdots \mathbf{M}_{t_0 \rightarrow t_1} \mathbf{K}_m \delta \mathbf{x}_0$$

$$\mathbf{d}_k = \mathbf{y}_k^o - h (\mathbf{k}_h \{m_{t_0 \rightarrow t_k} [\mathbf{k}_m (\mathbf{x}_0)]\})$$

$$\mathbf{B} = \mathbf{K}_b \mathbf{D} \mathbf{C} \mathbf{D} \mathbf{K}_b^\top$$

# Variable changes



Sets of variables:

Background: the variables which you end up with an analysis of. Typically chosen to interact well with the forecast model being restarted.

Control increment: the variables of  $\delta \mathbf{x}_0$ , chosen based on various considerations.

Model: the variables that the model and linear model need, e.g. staggered winds.

B matrix variables: the variables used in the B matrix, e.g. unbalanced stream function and velocity potential.

# VarChaC2MFV3JEDI



```
public :: fv3jedi_varcha_c2m
public :: create
public :: delete
public :: multiply
public :: multiplyadjoint
public :: multiplyinverse
public :: multiplyinverseadjoint
```

Increment containing  
control variables comes  
in, increment with  
model variables goes  
out. The base class  
handles the allocation  
and deallocation either  
side.

```
subroutine multiply(self,geom,xctl,xmod)

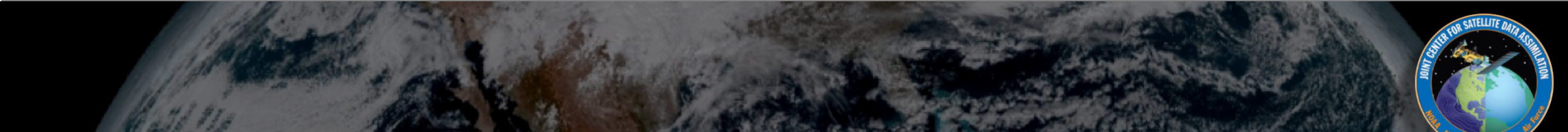
implicit none
type(fv3jedi_varcha_c2m), intent(in) :: self
type(fv3jedi_geom), target, intent(inout) :: geom
type(fv3jedi_increment), intent(inout) :: xctl
type(fv3jedi_increment), intent(inout) :: xmod

!Ps
xmod%ps = xctl%ps

!Tracers
xmod%qi = xctl%qic
xmod%ql = xctl%qlc
xmod%o3 = xctl%o3c

!Tangent linear of analysis (control) to model variables
call control_to_model_tlm(geom, xctl%psi, xctl%chi, xctl%tv, xctl%qc, &
                           xmod%ua , xmod%va , xmod%t , xmod%q , &
                           self%tvtraj,self%qtraj,self%qsattraj )

end subroutine multiply
```



# Get Values



# GetValues



In order to maintain the separation of concerns the observation operator is split into a model dependent parts and model agnostic part.

$$\begin{aligned} y^o &= h(x) \\ &= h_{obs} [h_{mod}(x)] \end{aligned}$$

The model dependent part might involve interpolation, field of view calculations and variable transforms.

The intermediate state after computing the model dependent part of the observation operator are known as GeoVaLs (Geophysical Values at observation Locations).

$$GeoVaLs = h_{mod}(x)$$

These are model states interpolated to observation locations and converted to the variables requested by the observation operator.

# GetValues



## Fortran class definitions

```
type getvalues
integer :: dummy
contains
  procedure :: create
  procedure :: delete
  procedure :: fill_geovals
end type getvalues
```

```
type getvalues_tlad
integer :: dummy
contains
  procedure :: create
  procedure :: delete
  procedure :: set_trajectory
  procedure :: fill_geovals_tl
  procedure :: fill_geovals_ad
end type getvalues_tlad
```

# GetValues



```
subroutine create(self, geom, vars, locs)

class(fv3jedi_getvalues), intent(inout) :: self
type(fv3jedi_geom),      intent(in)    :: geom
type(oops_variables),    intent(in)    :: vars
type(ufo_locs),          intent(in)    :: locs
```

```
end subroutine create
```

```
! -----
```

```
subroutine delete(self)
```

```
class(fv3jedi_getvalues), intent(inout) :: self
```

```
end subroutine delete
```

```
subroutine fill_geovals(self, state, t1, t2, geovals)
```

```
class(fv3jedi_getvalues), intent(in)      :: self
type(fv3jedi_state),      intent(in)      :: state
type(datetime),           intent(in)      :: t1
type(datetime),           intent(in)      :: t2
type(ufo_geovals),        intent(inout)    :: geovals
```

```
end subroutine fill_geovals
```

# LinearGetValues



```
subroutine set_trajectory(self, state, t1, t2, geovals)
```

```
class(fv3jedi_getvalues_tlad), intent(in)    :: self
type(fv3jedi_state),          intent(in)    :: state
type(datetime),              intent(in)    :: t1
type(datetime),              intent(in)    :: t2
type(ufo_geovals),           intent(inout) :: geovals
```

```
end subroutine set_trajectory
```

```
! -----
```

```
subroutine fill_geovals_tl(self, inc, t1, t2, geovals)
```

```
class(fv3jedi_getvalues_tlad), intent(in)    :: self
type(fv3jedi_increment),       intent(in)    :: inc
type(datetime),               intent(in)    :: t1
type(datetime),               intent(in)    :: t2
type(ufo_geovals),            intent(inout) :: geovals
```

```
end subroutine fill_geovals_tl
```

```
type :: fv3jedi_getvalues_traj
integer :: bumpid, ngrid
logical :: noobs
real(kind=kind_real), allocatable :: t(:,:,:)
real(kind=kind_real), allocatable :: q(:,:,:)
type(bump_type) :: bump
logical :: lalloc = .false.
end type fv3jedi_getvalues_traj
```



# GetValues: algorithm



Compute weights for interpolation

Loop over UFO variables

    Select case on variable

        Convert variable and prepare interpolation

        Loop over levels

            Interpolate to locations  
        end (levels)

End (variables)

# getValues: prepare state/increment variable



Loop over variables

Flag on whether to interpolate

Set number of levels for variable and interpolation flag.

Transform the variable if need be

Some variables use integration or aren't float.

ABORT

```
do jvar = 1, vars%nv
  do_interp = .false.
  select case (trim(vars%fldnames(jvar)))
    case ("eastward_wind")
      nvl = npz
      do_interp = .true.
      geoval => state%ua
    case ("virtual_temperature")
      nvl = npz
      do_interp = .true.
      call T_to_Tv(geom, state%t, state%q, geovalm)
      geoval => geovalm
    case ("Soil_Type")
      nvl = 1
      do_interp = .false.
      obs_state(:,1) = real(soil_type, kind_real)
    case default
      call abort1_ftn(trim(myname)//"unknown variable: "//trim(vars%fldnames(jvar)))
```

GeoVals are not part of the Model Space but currently have to be allocated by the model. This is because one of the dimensions is the number of vertical levels. The plan is to move this to the GeoVals constructor at some point and request this from the model geometry instead.

The model only sees GeoVals in GetValues so this is where the allocation occurs. E.g.:

```
if (.not.allocated(gom%geovals(jvar)%vals)) then
  gom%geovals(jvar)%nval = gvlev

  allocate(gom%geovals(jvar)%vals(gom%geovals(jvar)%nval,gom%geovals(jvar)%nobs))
  gom%geovals(jvar)%vals = 0.0_kind_real

  if (lastvar) gom%linit = .true.
endif
```

# Interpolation



Interpolation is needed in several places in the model interface. It's required in `GetValues` for interpolating to observation locations but also in `State` and `Increment`, for example to support data assimilation algorithms that support increments at varying resolution.

JEDI provides general unstructured interpolation options via BUMP (B Matrix Unstructured Mesh Package) and via a stand alone unstructured interpolation routine. In the future we also plan to support interpolation using Atlas. In addition each model can implement their own interpolation methods.



# Generic interpolation: creating weights



Latitudes and longitudes for both BUMP and unstructured interpolation are unstructured, rank 1 vectors where order is not important. Input lats and lons do not have to be on the same processor as the output lats and lons.

BUMP interpolation from SABER

```
call bump%setup_online( f_comm, ngrid_in, 1, 1, 1, lon_in_us, lat_in_us, area, vunit, lmask, &  
                        nobs=ngrid_ou, lonobs=lon_ou, latobs=lat_ou)
```

Unstructured interpolation from OOPS

```
call self%unsinterp%create( geom_in%f_comm, self%nnearest, trim(us_interp_type), &  
                            geom_in%ngrid, rad2deg*geom_in%lat_us, rad2deg*geom_in%lon_us, &  
                            geom_ou%ngrid, rad2deg*geom_ou%lat_us, rad2deg*geom_ou%lon_us )
```

# Generic interpolation: apply



```
call self%bump%apply_obsop(field_in, field_ou)
```

```
call self%unsinterp%apply(field_in, field_ou)
```

# Future of model interfacing



As development has evolved it has become clear that it should be possible to make some of the interfacing more generic and share code across models.

MAGIC (Model Agnostic Grid Interface Construct) by Rahul Mahajan explores the possibility of having some components be generic, or using a base class, to limit duplicate work across model interfaces.

One possibility is to leverage the capabilities in the Atlas. That way the Geometry, State and Increment can just be Atlas structures and have identical source code across interfaces.

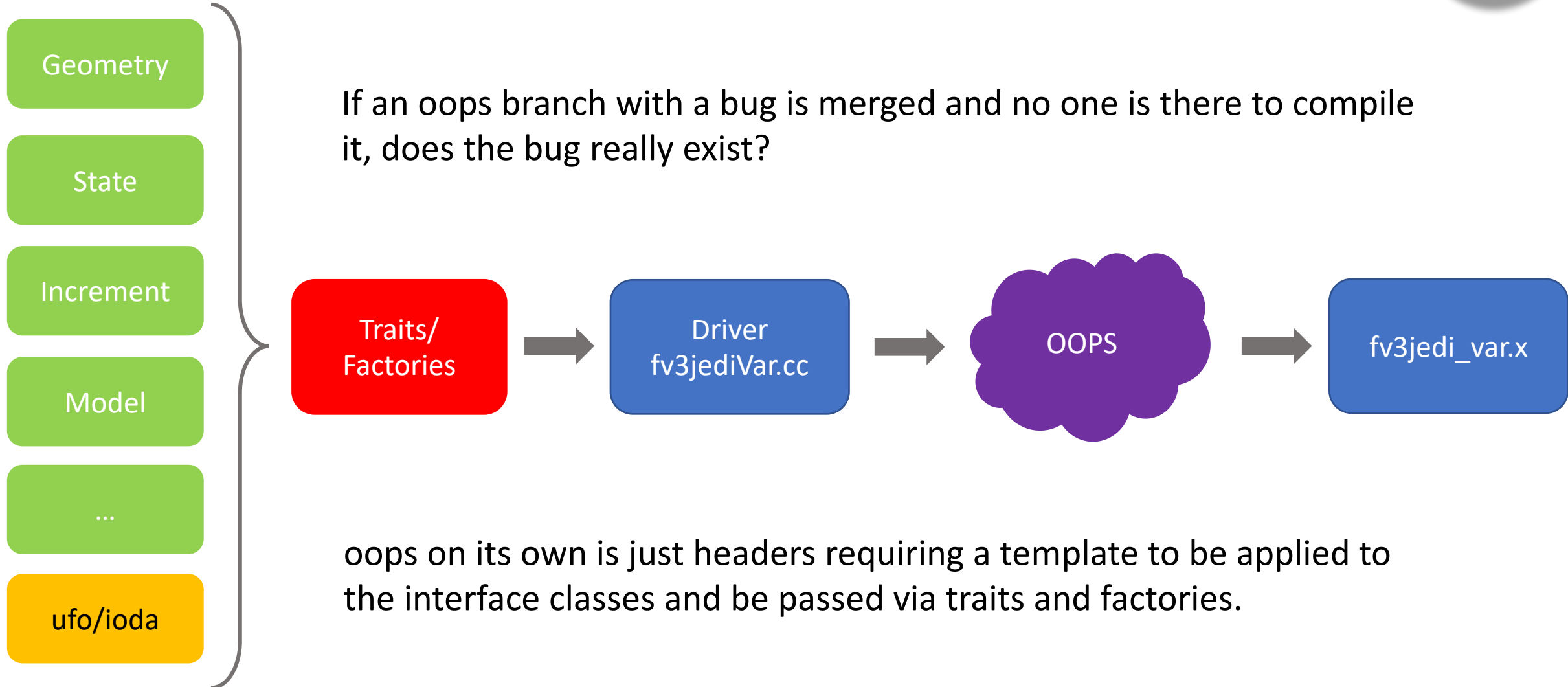
This will also enable the possibility of a completely generic GetValues class.

# Building an application





# Building an application driver



# fv3jediVar.cc application driver



```
#include "FV3JEDITraits.h"
#include "instantiateLocalizationFactory.h"
#include "instantiateFV3JEDIVarChangeFactory.h"
#include "instantiateObsFilterFactory.h"
#include "oops/runs/Variational.h"
#include "RunFV3JEDI.h"
```

```
int main(int argc, char ** argv) {
    fv3jedi::RunFV3JEDI run(argc, argv);
    fv3jedi::instantiateLocalizationFactory();
    fv3jedi::instantiateFV3JEDIVarChangeFactory();
    fv3jedi::instantiateObsFilterFactory();
    oops::Variational<fv3jedi::FV3JEDITraits> var;
    run.execute(var);
    return 0;
}
```

Include the model traits

Include the factories

Include the main application

Pass config (YAML)

Initialization step (FMS etc)

Instantiate factories

Create application object

Execute application

# Run



```
class Run : public eckit::Main {  
public:  
    Run(int argc, char** argv);  
    virtual ~Run();  
    void execute(const Application &);  
  
protected:  
    const eckit::Configuration & config() const {return *config_;}  
  
private:  
    boost::scoped_ptr<const eckit::YAMLConfiguration> config_;  
    boost::scoped_ptr<util::Timer> timer_;  
};
```

Inheritance from the base class  
Run

This can do generic initialization  
such as MPI init and prepare  
generic monitoring tools.

In turn inherits eckit::Main.

Execute runs the application  
and diagnostics.

# Variational.h



```
template <typename MODEL> class Variational : public Application {
    typedef Geometry<MODEL>          Geometry_;
    typedef Model<MODEL>              Model_;
    typedef State<MODEL>              State_;

public:
// -----
    Variational() {
        instantiateCostFactory<MODEL>();
        instantiateCovarFactory<MODEL>();
        instantiateMinFactory<MODEL>();
        instantiateObsErrorFactory<MODEL>();
        instantiateObsFilterFactory<MODEL>();
        instantiateTlmFactory<MODEL>();
        instantiateVariableChangeFactory<MODEL>();
    }
// -----
    virtual ~Variational() {}
// -----
    int execute(const eckit::Configuration & fullConfig) const {
// Setup resolution
        const eckit::LocalConfiguration resolConfig(fullConfig, "resolution");
        const Geometry_ resol(resolConfig);

// Setup Model
        const eckit::LocalConfiguration modelConfig(fullConfig, "model");
        const Model_ model(resol, modelConfig);
        Log::trace() << "Variational: model has been set up" << std::endl;
    }
};
```



# Run execute



```
void Run::execute(const Application & app) {
    int status = 1;
    Log::info() << "Run: Starting " << app << std::endl;
    try {
        status = app.execute(*config_);
    }
    catch(const eckit::Exception & e) {
        status = 1;
        Log::error() << e.what() << " caught in " << Here() << std::endl;
        Log::error() << "Exception: " << app << " terminating..." << std::endl;
        eckit::Exception::exceptionStack(eckit::Log::error(), true);
    }
    catch(const std::exception & e) {
        status = 1;
        Log::error() << "Exception: " << e.what() << std::endl;
        Log::error() << "Exception: " << app << " terminating..." << std::endl;
    }
    catch(...) {
        status = 1;
        Log::error() << "Unknown exception: " << app << " terminating..." << std::endl;
    }
    Log::info() << "Run: Finishing " << app << std::endl;

    // Performance diagnostics
    util::ObjectCountHelper::stop();
    util::TimerHelper::stop();

    Log::info() << "Run: Finishing " << app << " with status = " << status << std::endl;
    if (status) ::exit(status);
}
```

Receives and application

Calls application execute

Checking of proper run

Output some diagnostics

# FV3-JEDI Traits



## OOPS level State.h interface

```
template <typename MODEL>
class State : public util::Printable,
              private util::ObjectCounter<State<MODEL> > {
    typedef typename MODEL::State      State_;

public:
    State_ & state() {return *state_;}
    const State_ & state() const {return *state_;}

private:
    boost::scoped_ptr<State_> state_;
};
```

FV3-JEDI Templates passed  
in through Traits. Basically  
just a list of implemented  
classes.

```
struct FV3JEDITraits {
    static std::string name() {return "FV3JEDI";}
    static std::string nameCovar() {return "FV3JEDIstatic";}

    typedef fv3jedi::GeometryFV3JEDI      Geometry;
    typedef fv3jedi::StateFV3JEDI         State;
    typedef fv3jedi::IncrementFV3JEDI     Increment;
    typedef fv3jedi::ModelBiasFV3JEDI     ModelAuxControl;
    typedef fv3jedi::ModelBiasIncrementFV3JEDI ModelAuxIncrement;
    typedef fv3jedi::ModelBiasCovarianceFV3JEDI ModelAuxCovariance;
    typedef fv3jedi::GetValuesTrajFV3JEDI InterpolatorTraj;

    typedef ufo::ObsOperator              ObsOperator;
    typedef ufo::LinearObsOperator        LinearObsOperator;
    typedef ufo::ObsBias                  ObsAuxControl;
    typedef ufo::ObsBiasIncrement         ObsAuxIncrement;
    typedef ufo::ObsBiasCovariance        ObsAuxCovariance;
    typedef ufo::GeoVaLs                  GeoVaLs;

    typedef ioda::ObsSpace                ObsSpace;
    typedef ioda::ObsVector               ObsVector;
    typedef ioda::Locations               Locations;
};
```

# Factory instantiation



Instantiate the change of variable designated by VarChaC2MFV3JEDI. In the YAML we need to call as “Control2Model”

Factory: the class VarChaC2MFV3JEDI is then implemented as normal.

```
void instantiateFV3JEDIVarChangeFactory() {  
    static oops::LinearVariableChangeMaker<fv3jedi::FV3JEDITraits,  
        oops::LinearVariableChange<fv3jedi::FV3JEDITraits,  
            fv3jedi::VarChaC2MFV3JEDI> >  
        makerVarChangeFV3JEDI_("Control2Model");  
}
```

YAML: choose the subclass and the variables to be allocated.

```
- varchange: Control2Model  
  inputVariables:  
    variables: [ua, va, t, ps, q, qi, ql, o3]  
  outputVariables:  
    variables: [psi, chi, tv, ps, qc, qic, qlc, o3c]
```

# C++/Fortran binding





# Binding: C++ side



## GeometryFV3JEDI.cc

```
GeometryFV3JEDI::GeometryFV3JEDI(const eckit::Configuration & conf) {  
    const eckit::Configuration * configc = &conf;  
    stageFv3Files(conf);  
    fv3jedi_geo_setup_f90(keyGeom_, &configc);  
    removeFv3Files();  
}
```

## GeometryFV3JEDIFortran.h

```
extern "C" {  
    void fv3jedi_geo_setup_f90(F90geom &,  
                               const eckit::Configuration * const *);  
}  
}
```

# Binding: Fortran side



## fv3jedi\_geom\_interface\_mod.F90

```
subroutine c_fv3jedi_geo_setup(c_key_self, c_conf) bind(c,name='fv3jedi_geo_setup_f90')

implicit none
integer(c_int), intent(inout) :: c_key_self
type(c_ptr), intent(in)      :: c_conf

type(fv3jedi_geom), pointer :: self

call fv3jedi_geom_registry%init()
call fv3jedi_geom_registry%add(c_key_self)
call fv3jedi_geom_registry%get(c_key_self,self)

call create(self,c_conf)

end subroutine c_fv3jedi_geo_setup
```

} Access to the object is through a linked list

**Integer Key comes in, pointer to an object gets passed.**

# LinkedList inclusion



At the `interface_mod` level the Linked List is created for the Fortran version of the object.

`linkedList_i.f` contains the list of objects and `linkedList_c.f` contains the methods for manipulating and accessing the current object in the linked list.

```
module fv3jedi_geom_interface_mod

use fv3jedi_geom_mod

implicit none
private
public :: fv3jedi_geom_registry

#define LISTED_TYPE fv3jedi_geom
#include "linkedList_i.f"

type(registry_t) :: fv3jedi_geom_registry

contains

#include "linkedList_c.f"
```

# linkedList\_i.f



Linked list node is where an object is actually stored in memory. It also contains a pointer to the next element.

Class containing pointer to the head node.  
Methods for accessing that object.

!> Node of a linked list

```
type :: node_t
  integer          :: key
  type(LISTED_TYPE) :: element
  type(node_t), pointer :: next => NULL()
end type
```

!> Registry type

```
type :: registry_t
  logical          :: l_init = .false.
  integer          :: count  = 0
  type(node_t), pointer :: head => NULL()
contains
  procedure :: init => init_
  procedure :: finalize => finalize_
  procedure :: add => add_
  procedure :: get => get_
  procedure :: remove => remove_
end type
```



# LinkedList\_c.f: initilaize



If linked list not initialized associate the head node and set the flags.

```
subroutine init_(self)
  class(registry_t) :: self

  !set count to zero and allocate the head of the list
  if(.not.self%l_init.or..not.associated(self%head)) then
    self%count = 0
    allocate(self%head)
    nullify(self%head%next)
    self%l_init=.true.
  endif

end subroutine
```

# LinkedList\_c.f: add



Key comes in from OOPS. Adding an object to the linked list so 'up the counter' and set the key.

Then allocate the next element. This is the actual allocation of memory for the object.

Associate a pointer to the next element in the linked list.

```
subroutine add_(self,key)

  class(registry_t) :: self
  integer            :: key

  type(node_t), pointer :: next

  self%count = self%count+1
  key = self%count

  allocate(next)
  next%key = key

  next%next => self%head%next
  self%head%next => next

end subroutine
```

# LinkedList\_c.f: get



Pointer comes in which needs to be associated with the object in the position in the linked list associated with the key.

Do while loop sweeps the linked list until the key matches the point in the linked list.

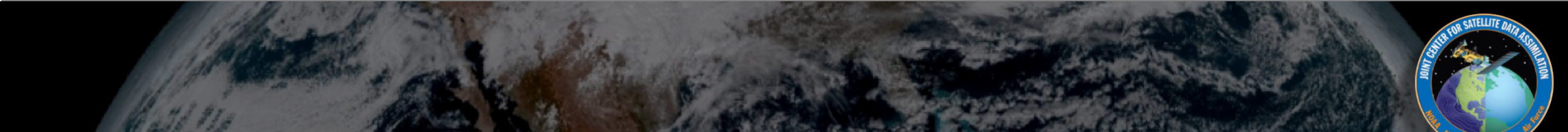
```
subroutine get_(self,key,ptr)
  class(registry_t)          :: self
  integer                    :: key
  type (LISTED_TYPE), pointer :: ptr

  type(node_t), pointer :: next

  next => self%head
  ptr => NULL()

  do while(associated(next))
    next=>next%next
    if(key.eq.next%key) then
      ptr => next%element
      exit
    endif
  enddo

end subroutine
```



Questions?